

Note $\mathcal{X}(M) = \Gamma(TM)$.

in fact, $C^\infty(M)$ -module:

$$(f\sigma)(p) = f(p)\sigma(p)$$



17. IV.23

Reduction of Structure

Recall that a vector bundle $\begin{matrix} E \\ \downarrow \pi \\ X \end{matrix}$ may be specified by cocycle data: open cover $\{V_\alpha \mid \alpha \in A\}$ of X + transition fns

$$\tau_{\alpha\beta}: V_\alpha \cap V_\beta \longrightarrow GL_k \mathbb{R}$$

satisfying the cocycle condition: $\forall \alpha, \beta, \gamma \in A$

$$\tau_{\alpha\gamma} = \tau_{\beta\gamma} \tau_{\alpha\beta}$$

Defn Let $G \subseteq GL_k \mathbb{R}$, $\pi: E \rightarrow M$ vb of rank k on M . A reduction of the structure group of E to G is a

$GL_k \mathbb{R}$ -cocycle representing the iso class of E , all of whose transition maps are valued in G .

E.g. • $G = GL_k^+ \mathbb{R} = \det^{-1}(\mathbb{R}_{>0}) \subseteq GL_k \mathbb{R}$

If E admits a $GL_k^+ \mathbb{R}$ -cocycle call it orientable.

If TM is orientable, call M orientable.

• $G = O(k) \subseteq GL_k \mathbb{R}$

If E admits an $O(k)$ -cocycle, then we can endow each of its fibers with an inner product and transition data will respect this.

If TM has structure gp reduced to $O(n)$, call

M a Riemannian manifold and say M has been given a Riemannian structure.

Fact Every smooth mfd admits a Riemannian str.

Twisting Fix a representation (i.e. homomorphism)

$\rho: GL_k(\mathbb{R}) \rightarrow GL_m(\mathbb{R})$. Composing transition data for $E \downarrow \pi$

with ρ gives new cocycles

$$\begin{array}{ccc} \rho \circ \tau_{\alpha\beta} : V_\alpha \cap V_\beta & \longrightarrow & GL_m \mathbb{R} \\ \tau_{\alpha\beta} \downarrow & & \uparrow \rho \\ & GL_k \mathbb{R} & \end{array}$$

$$\begin{array}{ccc} E & \longrightarrow & E^\rho \\ \uparrow & & \uparrow \\ \Gamma_k k & & \Gamma_k m \\ \text{vb on } M & & \text{vb on } M \end{array}$$

The associated vb on M is the ρ -twisting of E .

E.g. • $\det: GL_k \mathbb{R} \rightarrow GL_1 \mathbb{R} = \mathbb{R}^* \rightsquigarrow \det E$ line bundle on M
 $\Lambda^k E$

• $GL_n \mathbb{R} \rightarrow GL_n \mathbb{R} \rightsquigarrow E^*$ dual of E
 $A \mapsto (A^{-1})^T$

Local & Global Frames

$U \subseteq M$ open, $\begin{matrix} E \\ \pi \downarrow \\ M \end{matrix}$ vb. of rank k

$(\sigma_1, \dots, \sigma_k) \in \Gamma(E, U)^k$ is a local frame if $\sigma_1(p), \dots, \sigma_k(p)$ is a basis of $E_p \forall p \in U$,

$\begin{matrix} \sigma_i \dashrightarrow E \\ \downarrow \pi \\ U \subseteq M \end{matrix}$

local sections of E over U

global frame when $U=M$.

Note Frame for $M =$ frame for TM .

Eg. • Trivial bundles $M \times \mathbb{R}^k$ admit the global frame

\downarrow
 M

$(\tilde{e}_1, \dots, \tilde{e}_k)$ where $\tilde{e}_i(p) = (p, e_i)$.

• Local trivializations induce local frames:

$$\pi^{-1}U \xrightarrow[\cong]{\Phi} U \times \mathbb{R}^k \quad \text{so define } \sigma_i = \Phi^{-1} \cdot \tilde{e}_i$$

Prop Every smooth local/global frame for a smooth ub is associated with a smooth local/global trivialization.

pf p. 259 \square

Cor A smooth manifold is parallelizable iff TM is trivial. \square

↑
defined as TM
admitting a global
frame

The Cotangent Bundle

Duals V an \mathbb{R} -vector space.

$V^* := \text{Hom}_{\mathbb{R}}(V, \mathbb{R}) = \{ \underbrace{\omega: V \rightarrow \mathbb{R}}_{\text{a covector}} \mid \omega \text{ linear} \}$ is the dual space of V .

Given basis v_1, \dots, v_n of V let $v_1^*, \dots, v_n^* \in V^*$ be the covectors defined by $v_i^*(v_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$ (then extended linearly).

Then v_1^*, \dots, v_n^* is the dual basis (to (v_i)) of V^* .

Given $A: V \rightarrow W$ linear, the dual of A is

$$A^*: W^* \longrightarrow V^*$$

$$\begin{array}{ccc} W & & V \\ \omega \downarrow & \longmapsto & A \downarrow \\ \mathbb{R} & & \mathbb{R} \end{array} \begin{array}{c} \nearrow A \\ \searrow \omega \end{array}$$

i.e. $(A^*w)(v) = w(Av)$ for $v \in V, w \in W^*$.

Have $(A \circ B)^* = B^* \circ A^*$ and $\text{id}_V^* = \text{id}_{V^*}$ so duality is

a functor $\text{Vect}_{\mathbb{R}}^{\text{op}} \longrightarrow \text{Vect}_{\mathbb{R}}$.

Double dual $V^{**} = (V^*)^*$. Have

$$\begin{array}{ccc} \zeta = \zeta_V : V & \longrightarrow & V^{**} \\ v \longmapsto & & \downarrow \zeta(v) \\ & & \mathbb{R} \end{array} \quad \begin{array}{c} \omega : V \rightarrow \mathbb{R} \\ \downarrow \\ \omega(v) \end{array}$$

Then $\zeta : \text{id}_{\text{Vect}_{\mathbb{R}}} \Rightarrow (\)^{**}$ is a natural transformation:

for $A: V \rightarrow W$ linear,

$$\begin{array}{ccc}
 V & \xrightarrow{A} & W \\
 \cong_V \downarrow & & \downarrow \cong_W \\
 V^{**} & \xrightarrow{A^{**}} & W^{**}
 \end{array}
 \quad \text{commutes.}$$

Prop If $\dim V < \infty$, then $\cong: V \xrightarrow{\cong} V^{**}$ is a natural isomorphism.

- $V \not\cong V^{**}$ for infinite dim'l vector spaces
- $V \cong V^*$ for V finite dim'l, but the iso is not natural.

Tangent covectors on manifolds

$p \in M$ smooth mfld, the cotangent space at p is

$$T_p^* M := (T_p M)^*$$

The transition maps for T^*M are inverse-transpose of those for TM .

Write $\mathcal{X}^*(M) = \Gamma(T^*M)$ for smooth covector fields on M .

The differential $\Gamma(T^*M, M)$

For $f \in C^\infty(U)$, write $df \in \mathcal{X}^*(U)$ defined by $\left. \begin{array}{l} T^*M \\ \downarrow \omega \\ M \end{array} \right\} \omega_p : T_p M \rightarrow \mathbb{R}$
 open in M linear

$$df : U \longrightarrow T^*M$$

$$p \longmapsto \begin{array}{ccc} & T_p M & v \\ & \downarrow df_p & \downarrow \\ & \mathbb{R} & df_p(v) = \underbrace{vf} \end{array}$$

using $T_p M = \text{Der}_p(C^\infty(U))$

Call df the differential covector field of f .

Take (x^i) smooth coords on $U \subseteq M$ open.

Get a frame $\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$ of $TM|_U$ with dual frame $\lambda^1, \dots, \lambda^n$ of $T^*M|_U$ ($\lambda^i|_p = \left(\frac{\partial}{\partial x^i}\Big|_p\right)^*$)

Have $df_p = \sum A_i(p) \lambda^i|_p$ for some fns $A_i: U \rightarrow \mathbb{R}$.

By defn of df ,

$$A_i(p) = df_p\left(\frac{\partial}{\partial x^i}\Big|_p\right) = \frac{\partial}{\partial x^i}\Big|_p f = \frac{\partial f}{\partial x^i}\Big|_p$$

Thus $df_p = \sum \frac{\partial f}{\partial x^i}(p) \lambda^i|_p$ $\dots \dots \dots$ $\sum \nabla f_p$ in x^i coord system

In particular, applied to $x^i: U \rightarrow \mathbb{R}$ coord fn, get

$$dx^j|_p = \sum_i \frac{\partial x^j}{\partial x^i}(p) \lambda^i|_p = \lambda^j|_p$$

I.e., dx^1, \dots, dx^n is the dual frame of $\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$.

Thus $df_p = \sum \frac{\partial f}{\partial x^i}(p) dx^i|_p \in T_p^*M$

and $df = \sum \frac{\partial f}{\partial x^i} dx^i \in \mathcal{X}^*(U)$.

$$\int f(x) \underline{dx}$$

Why covectors? They give us coordinate-free versions of gradients!

$$\begin{array}{ccc}
 TM & \xrightarrow{dF} & TN \\
 \downarrow & & \downarrow \\
 M & \xrightarrow{F} & N
 \end{array}$$

$$\begin{array}{ccc}
 TM & \xrightarrow{df} & T\mathbb{R} = \mathbb{R} \times \mathbb{R} \\
 \downarrow & & \downarrow \\
 M & \xrightarrow{f} & \mathbb{R}
 \end{array}$$

$$\stackrel{\text{vs}}{=} df \in \mathcal{X}^*(M)$$

$$\begin{array}{ccc}
 T_p M & \longrightarrow & \{p\} \times \mathbb{R} \\
 v & \longmapsto & (p, vf)
 \end{array}$$

$$\begin{array}{ccc}
 T^*M & & \\
 \downarrow & \curvearrowright & df \\
 M & \dashrightarrow &
 \end{array}$$

E.g. $f: \mathbb{R}^2 \rightarrow \mathbb{R}$
 $(x, y) \mapsto x^2 y \cos x$

$$df = \frac{\partial(x^2 y \cos x)}{\partial x} dx + \frac{\partial(x^2 y \cos x)}{\partial y} dy$$

$$= (2xy \cos x - x^2 y \sin x) dx + (x^2 \cos x) dy$$

while $\nabla f = (\quad , \quad)$

Prop $f, g \in C^\infty(M)$, $a, b \in \mathbb{R}$

(a) $d(af + bg) = a df + b dg$

(b) $d(fg) = f dg + g df$

(c) $d(f/g) = \frac{1}{g^2} (g df - f dg)$ on $g \neq 0$

(d) $\text{im } f \in J \subseteq \mathbb{R}$, $h: J \rightarrow M$
 $\Rightarrow d(h \circ f) = (h' \circ f) df$

(e) $f \text{ const} \Rightarrow df = 0$. □