

Good news:  $\mathcal{X}$  is functorial in diffeomorphisms!

I.e.  $F: M \xrightarrow{\cong} N$  and  $X \in \mathcal{X}(M)$  then  $\exists! F_* X \in \mathcal{X}(N)$

s.t.  $(F_* X)_q = dF_{F^{-1}(q)} X_{F^{-1}(q)}$ ; moreover,  $\text{id}_* X = X$  and

if  $G: N \xrightarrow{\cong} P$  then  $(G \circ F)_* X = G_* (F_* X)$ .

$$\begin{array}{ccc}
 TM & \xrightarrow[\cong]{dF} & TN \\
 \left( \begin{array}{ccc} \uparrow & & \uparrow \\ \downarrow \pi_M & & \downarrow \pi_N \\ M & \xrightarrow[\cong]{F} & N \end{array} \right) & & F_* X = dF \cdot X \circ F^{-1}
 \end{array}$$

Call  $F_* X$  the pushforward of  $X$  along  $F$ .

Since  $X$  and  $F_* X$  are  $F$ -related,  
 $X(f \circ F) = (F_* X)_f \cdot F$ .

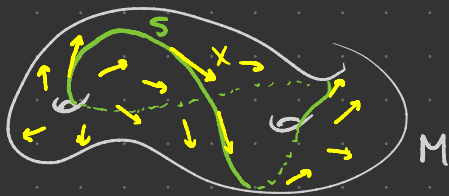
See pp. 183-184 for detailed comp'n of  $F_* X$ .

## Vector fields & submanifolds

$S \subseteq M$  immersed or embedded submfld

For  $p \in S$ ,  $X \in \mathfrak{X}(M)$  call  $X$  tangent to  $S$  at  $p$  when

$$X_p \in T_p S \subseteq T_p M$$



Prop  $S \subseteq M$  emb submfld. Then

$X \in \mathfrak{X}(M)$  is tangent to  $S$  iff

$$Xf|_S = 0 \quad \forall f \in C^\infty(M) \text{ s.t. } f|_S = 0.$$

□

Directional derivs in directions  
tangent to  $S$  are 0 on  
fns constant on  $S$ .

Note  $S \subseteq M$  imm submfld,

$X \in \mathfrak{X}(M)$  tangent to  $S$ ,  
then  $\exists! X|_S \in \mathfrak{X}(S)$

that is  $\iota$ -related to  $X$   
( $\iota: S \hookrightarrow M$ )

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## Lie brackets

Recall  $\mathfrak{X}(M) \cong \left\{ \begin{array}{l} \text{derivations } C^\infty(M) \rightarrow C^\infty(M) \\ X \mapsto (f \mapsto Xf) \end{array} \right\}$

Given  $X, Y \in \mathfrak{X}(M)$ , we may form  $XY$  &  $YX$  as composites:

$$XY: f \mapsto X(Yf)$$

$$YX: f \mapsto Y(Xf)$$

These are fns  $XY, YX: C^\infty(M) \rightarrow C^\infty(M)$  but not derivations.

But the Lie bracket

$$[X, Y] := XY - YX: f \mapsto X(Yf) - Y(Xf)$$

is a derivation  $C^\infty(M) \rightarrow C^\infty(M)$  so  $[X, Y] \in \mathfrak{X}(M)$  !

Pf  $[X, Y](fg) = (XY)(fg) - (YX)(fg)$

$$= X(fYg) + (Yf)g - Y(fXg) + (Xf)g$$

$$= \cancel{f \cdot XYg} + \cancel{Xf \cdot Yg} + \cancel{Yf \cdot Xg} + XYf \cdot g - (\cancel{f \cdot YXg} + \cancel{Yf \cdot Xg} + \cancel{Xf \cdot Yg} + YXf \cdot g)$$

$$= f[X, Y]g + [X, Y]f \cdot g$$

so  $[X, Y]$  is a derivation.  $\square$

Later  $[X, Y]$  is the "Lie derivative" — directional deriv of  $Y$  along  $X$ .



Prop  $X, Y \in \mathfrak{X}(M)$ ,  $X = \sum_i X^i \frac{\partial}{\partial x^i}$ ,  $Y = \sum_j Y^j \frac{\partial}{\partial x^j}$  for some smooth local coords  $(x^i)$  for  $M$ . Then

$$\begin{aligned} [X, Y] &= \sum_{i,j} \left( X^i \frac{\partial Y^j}{\partial x^i} - Y^j \frac{\partial X^i}{\partial x^j} \right) \frac{\partial}{\partial x^i} \\ &= \sum_j (X Y^j - Y X^j) \frac{\partial}{\partial x^j} \end{aligned}$$

Pf  $\frac{\partial^2}{\partial x^i \partial x^j} = \frac{\partial^2}{\partial x^j \partial x^i}$  on smooth fns.  $\square$

E.g.  $\left[ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0 \quad \forall i, j$

•  $X = x \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + x(y+1) \frac{\partial}{\partial z}$ ,  $Y = \frac{\partial}{\partial x} + y \frac{\partial}{\partial z} \in \mathfrak{X}(\mathbb{R}^3)$

Then  $[X, Y] = (X1 - Yx) \frac{\partial}{\partial x} + (X0 - Y1) \frac{\partial}{\partial y} + (Xy - Y[x(y+1)]) \frac{\partial}{\partial z}$

$$= (0-1) \frac{\partial}{\partial x} + 0 \frac{\partial}{\partial y} + (1-(y+1)) \frac{\partial}{\partial z}$$

$$= -\frac{\partial}{\partial x} - y \frac{\partial}{\partial z}$$

Prop Lie brackets are

- bilinear  $[aX+Y, Z] = a[X, Z] + [Y, Z]$

$$[X, aY+Z] = a[X, Y] + [X, Z] \quad \forall a \in \mathbb{R}, X, Y, Z \in \mathfrak{X}(M)$$

- antisymmetric  $[X, Y] = -[Y, X] \quad \forall X, Y \in \mathfrak{X}(M)$

They also satisfy the

- Jacobi identity  $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0 \quad \forall X, Y, Z$

and for  $f, g \in C^\infty(M)$ ,

$$[fX, gY] = fg[X, Y] + (fXg)Y - (gYf)X$$

The proof consists of comp's following from defns.  $\square$

A Lie algebra is an  $\mathbb{R}$ -vector space  $\mathfrak{g}$  together with a bilinear transformation  $[\cdot, \cdot]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$  which is antisymmetric and satisfies the Jacobi identity.

Thus  $\mathfrak{X}(M)$  is a Lie algebra!

The Lie algebra of a Lie group

$G$  a Lie group.  $X \in \mathfrak{X}(G)$  is left invariant when  $(L_g)_* X = X \quad \forall g \in G$ .

Write  $\text{Lie}(G) = \mathfrak{g} \subseteq \mathfrak{X}(G)$  for the  $\mathbb{R}$ -vector subspace of left-invariant vector fields on  $G$ .

Prop If  $X, Y \in \mathfrak{g}$ , then  $[X, Y] \in \mathfrak{g}$  so  $\mathfrak{g}$  is a Lie algebra.

Pf  $(L_g)_* [X, Y] = [(L_g)_* X, (L_g)_* Y] = [X, Y] \quad \square$

Naturality of  $[,]$ : If  $F: M \rightarrow N$  smooth,  $X_1, X_2 \in \mathcal{X}(M)$ ,  $Y_1, Y_2 \in \mathcal{X}(N)$  st.  $X_i$  is  $F$ -related to  $Y_i$ ,  $i=1,2$ , then  $[X_1, X_2]$  is  $F$ -related to  $[Y_1, Y_2]$ . (Apply to  $F = L_g$ .)

Pf  $X_1 X_2 (f \circ F) = X_1 ((Y_2 f) \circ F) = (Y_1 Y_2 f) \circ F$   
 $X_2 X_1 (f \circ F) = X_2 ((Y_1 f) \circ F) = (Y_2 Y_1 f) \circ F$   
 $\Rightarrow [X_1, X_2] (f \circ F) = X_1 X_2 (f \circ F) - X_2 X_1 (f \circ F)$   
 $= (Y_1 Y_2 f) \circ F - (Y_2 Y_1 f) \circ F$   
 $= ([Y_1, Y_2] f) \circ F. \quad \square$

A Lie algebra homomorphism is a linear map  $A: \mathfrak{g} \rightarrow \mathfrak{h}$  s.t.

$$A[X, Y] = [AX, AY] \quad \forall X, Y \in \mathfrak{g}.$$

E.g. •  $\mathfrak{gl}_n \mathbb{R} := \mathbb{R}^{n \times n}$  with  $[A, B] := AB - BA$

•  $\mathfrak{gl}_n \mathbb{C} := \mathbb{C}^{n \times n}$  as  $2n^2$ -dim- $\mathbb{R}$ -vs with  $[A, B] := AB - BA$

(Later we'll see these are  $\cong \text{Lie}(GL_n F)$  for  $F = \mathbb{R}, \mathbb{C}$  resp.)

Thm Let  $G$  be a Lie group. The evaluation map

$$\varepsilon: \text{Lie}(G) \longrightarrow T_e G$$

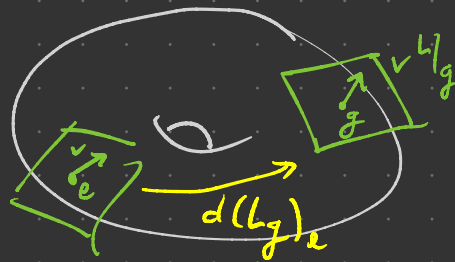
$$X \longmapsto X_e$$

is a vector space isomorphism. Thus  $\dim_{\mathbb{R}} \text{Lie}(G) = \dim G$ .

Pf  $\varepsilon$  is linear and if  $\varepsilon(X) = X_e = 0$  then  $X = 0$  b/c (by left-invariance)  $X_g = d(L_g)_e(X_e) = 0 \quad \forall g$ .

For surjectivity, let  $v \in T_e G$  be arbitrary and define

$$v^L|_g := d(L_g)_e(v)$$



$v^L$  is smooth: Suffices to show  $v^L f$

smooth  $\forall f \in C^\infty(G)$ . Take  $\gamma: (-\delta, \delta) \rightarrow G$  smooth with

$\gamma(0) = e$ ,  $\gamma'(0) = v$ . Then for  $g \in G$ ,

$$\begin{aligned} (v^L f)(g) &= v^L|_g f = d(L_g)_e(v) f = v(f \circ L_g) \\ &= \gamma'(0)(f \circ L_g) = \left. \frac{d}{dt} \right|_{t=0} (f \circ L_g \circ \gamma)(t) \end{aligned}$$

Define  $\varphi: (-\delta, \delta) \times G \rightarrow \mathbb{R}$

$$(t, g) \mapsto f \cdot L_g \circ \gamma(t) = f(g\gamma(t))$$

Then  $(v^L f)(g) = \frac{\partial \varphi}{\partial t}(0, g)$ . Since  $\varphi$  is smooth,  $v^L f$  is smooth. ✓

$v^L$  is left-invariant: WTS  $d(L_h)_g(v^L|_g) = v^L|_{hg} \quad \forall g, h \in G$ .

$$\begin{aligned} \text{By defn, } d(L_h)_g(v^L|_g) &= d(L_h)_g(d(L_g)_e v) \\ &= d(L_h \circ L_g)_e v \\ &= d(L_{hg})_e v \\ &= v^L|_{hg} \end{aligned}$$

Finally,  $\varepsilon(v^L) = v^L|_e = v$  so  $\varepsilon$  is surjective.  $\square$